DISCIPLINE SPECIFIC ELECTIVES (DSE-6)

CREDIT DISTRIBUTION, ELIGIBILITY AND PRE-REQUISITES OF THE COURSE

Course title & Code	Credits	Credit distribution of the course			Eligibility criteria	Pre-requisite of the course (if any)
		Lecture	Tutorial	Practical/ Practice		
Digital Control System ELDSE8F	**4**	**3**	**-**	**1**	**Class XII passed with Physics + Mathematics/Applied Mathematics + Chemistry OR Physics + Mathematics/Applied Mathematics + Computer Science/Informatics Practices**	**-**

Learning Objectives

This course introduces the students to fundamental concepts, principles and application of digital control system analysis and design. The topics cover classical control design as well as the modern control design methods

Learning outcomes

On successful completion of this course, student will be able to:

- Familiarize basic concepts for analysis of discrete-time domain systems.
- Use of pulse transfer function in discrete time systems.
- Stability analysis of digital control systems
- Design of compensators and controllers for desired time/frequency response.
- Design of estimators and observers

SYLLABUS OF ELDSE-8F **Total Hours- Theory: 45 Hours, Practicals: 30 Hours**

UNIT – I (11 Hours)
Digital Control System:
Overview of control systems (open-loop vs closed-loop), Introduction to digital control systems, Continuous-time vs discrete-time control systems, Sampling theory: Sampling theorem and Nyquist rate, Aliasing and anti-aliasing filters, Reconstruction using zero-order hold (ZOH), Quantization effects, Discrete-time signals and systems, Z-transform and pulse transfer functions

UNIT – II (11 Hours)
Stability Analysis:
Stability analysis of discrete-time systems: Jury's stability criterion, Stability analysis using bi-linear transformation, Time response of discrete-time systems-Transient and steady-state responses, Design of sampled data control system-Discrete Root locus analysis, Frequency domain analysis: Bode and Nyquist plots (for sampled systems), Concept of Lyapunov stability

UNIT – III (11 Hours)
Discrete State-space Analysis:
State variable model, State-space representations for discrete-time systems, canonical forms, the solution to discrete-time state-space equation, state transition matrix (STM), controllability, observability and stability of discrete state space models

UNIT – IV (12 Hours)
Design and Analysis of Discrete-time Control System*:
Design of digital control based on the frequency response method Bilinear Transformation and Design procedure in the w-plane, Lead, Lag and Lead-Lag compensators, and digital PID controllers, Deadbeat control design. Design of state feedback controller through pole placement – Necessary and sufficient conditions

*Note: Controllers like digital PID, state-feedback controllers are to be designed in the discrete-time domain to work with sampled data. Software tools like MATLAB/Simulink to simulate and optimize digital controllers.

Practical component (if any) – Digital Control System Lab
(Software Platform: MATLAB/Simulink or similar software)

Learning outcomes

The Learning Outcomes of this course are as follows:

- Perform experiments involving concepts of Digital Control for Automation
- Simulate different types of Digital Filters
- Perform the stability analysis of a system

- Design and simulate controllers using different techniques studied in theory paper
- Prepare the technical report on the experiments carried

LIST OF PRACTICALS (Total Practical Hours- 30 Hours)

1. Simulate the step response of a sampled-data (digital) control system
2. Stability analysis of a system using bode plot, root locus, and pole-zero gain representation
3. To obtain closed loop step and impulse response of a first order unity feedback system
4. Simulate a PD, PI and PID control design with a discrete-time controller. Compare the steady state response.
5. Simulate a frequency-domain controller to transform a continuous-time control design to a discrete-time control design
6. Design and simulate a Frequency-response controller or a State-feedback controller
7. Design of lead-lag compensator

Note: Students shall sincerely work towards completing all the above listed practicals for this course. In any circumstance, the completed number of practicals shall not be less than six.

Essential/recommended readings

1. Katsuhiko Ogata, "Discrete-Time Control Systems", 2nd Edition, Pearson, 1995, ISBN 9780130342812 (International), 9789332549661 (India).
2. M. Gopal, "Digital Control and State Variable Methods", 4th Edition, McGraw Hill Education, 2022, ISBN 9780071333276.
3. Benjamin C. Kuo, "Digital Control Systems", 2nd, Oxford University Press /Saunders College Publishing, 1995, ISBN 9780195104377/ 9780132111720.

Suggestive readings

1. C. Phillips, H. Nagle, A. Chakrabortty, "Digital Control System Analysis & Design", Pearson
2. G. F. Franklin, J. D. Powell and M. L. Workman, "Digital Control of Dynamic Systems", Addison Wesley, Pearson

Note: Examination scheme and mode shall be as prescribed by the Examination Branch, University of Delhi, from time to time.